

IEEE GRSS HDCRS Working Group High Performance and Disruptive Computing in Remote Sensing Summer school

Hyperspectral technology: inspiring ideas, challenges and opportunities

José López-Feliciano/Roberto Sarmiento Institute for Applied Microelectronics (IUMA) Part I: IntroductionPart II: HPC on-board SatellitesPart III: Our projects using HSI technology

Hyperspectral technology: inspiring ideas, challenges and opportunities

Part I: Introduction

José López-Feliciano/Roberto Sarmiento Institute for Applied Microelectronics (IUMA)



Outline

- The institute for Applied Microelectronics at ULPGC
- Why hyperspectral technology?
 - Some numbers
 - Applications
- Introduction to hyperspectral technology
 - The human eye
 - Multi- vs hyperspectral sensors
 - Types of hyperspectral sensors
- Ongoing projects
 - Space
 - Precision agriculture
 - Environment
 - Health

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Part III







CANARY ISLANDS

2,2 million POPULATION % FOREIGNERS 13% 13 million/yr TOURISTS



21 °C

18 °C

24 °C



13 million/yr 0,38 million

2,2 million

13%

24% 5,7 million/yr



TWO PUBLIC UNIVERSITIES:

Univ. Las Palmas de Gran Canaria (aprox. 20.000 students)

Univ. La Laguna (aprox. 23.000 students)

FOUR PRIVATE UNIVERSITIES:

Universidad del Atlántico Medio Universidad Fernando Pessoa Universidad de Las Hesperides Universidad Europea de Canarias



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DIVISIONS

Integrated Systems Design, ISD

Communication Systems, COM Maths, Graphics and Computation, MAGIC Microelectronics and Microsystems, MEMS Industrial Systems and CAD Tools, SICAD Information Technology, TI Microelectronic Technology, TME

FEATURES

More than 130 researchers More than 200 R&D projects













■Satellites □Airplanes □UAVs □Close-range



Human Eye Anatomy



Human Eye Anatomy



STEP 1 Light rays enter the eye through the **cornea**

STEP 2 The **iris** changes the size of the **pupil** from very small to large in order to regulate the amount of light that is entering

STEP 3 It continues through the lens and passes through the largest part of the eye filled with a jelly-like substance called **vitreous body**

STEP 4 The light finally reaches the **retina**, the membrane at the back wall of the eye which contains photoreceptors

STEP 5 The **photoreceptors** converts light into electrical signals which travel to the brain

Human Eye Anatomy





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RODS

Responsible of visión at low level light Scotopic visión Aprox. 100 million

CONES

Contain photopigments Active at higher light levels Photopic visión Perception of color Aprox. 7 million Three types: L (red) S (blue) M (green)

The proportion of the light recognized by these three cone types is interpreted by the brain, determining the colors













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Seeing the invisible





WHISKBROOM SCANNING

- Captures one single pixel at a time
- Very high spectral resolution

PUSHBROOM SCANNING

- Captures one line at a time
- Very high spectral resolution

SPECTRAL SCANNING

- Entire spatial information for all bands at a time
- Produces cubes slowly

SNAPSHOT SCANNING

- Fast for moving objects
- Limited spectral and spatial resolution



FEATURES

- Spectral range of 400-1000 / 400-780 nm
- High spatial resolution of 1024 pixels
- High image speed of 330 FPS (full range)
- Free wavelength selection from 224 bands within the camera coverage
- Built-in image correction
- Unified spectral calibration between units
- GigE or CameraLink standard interfaces
- Easy mounting to industrial environment

SPECTRAL RESPONSE




FEATURES

- Spectral range of 900-1700 nm
- High spatial resolution of 640 pixels
- High image speed
 670 FPS (full range) for GigE version
 527 FPS (full range) for CameraLink version
- Free wavelength selection from 224 bands within the camera coverage
- Built-in image correction
- Unified spectral calibration between units
- GigE or CameraLink standard interfaces
- Easy mounting to industrial environment

SPECTRAL RESPONSE





Hyperspec[®] SWIR

Wavelength Range (nm)	900-2500	
Aperture	F/2.0	
Entrance Slit Width	25 µm	
Dispersion/Pixel (nm/pixel)	6	
FWHM Slit Image	6.3 nm	
Slit Length	12 mm	
Spectral Resolution	12 nm	
Spectral Bands	267	
Spatial Bands	384	
Smile - Aberration-corrected	Yes	
Keystone - Aberration-corrected	Yes	
Detector	Stirling-cooled MCT	
Max. Frame Rate (Hz)	450	
Pixel Pitch	24 µm	
Read A/D	16-Bit	
Camera Control Interface	Base CameraLink and RS232	
Weight (lb / kg)	9.6 / 4.4	
Max. Power (W)	14.4	

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- Applications
- Compression
- Unmixing
- Reducing prices

- Applications
- Compression
- Unmixing
- Reducing prices
- Specially for on-board applications (i.e. satellites, drones...)
- Reduce the on-board memory requirements
- Communication channel capacity restrictions
- Reduce download time
- Lossless vs. Lossy vs. Near lossless compression
- Spatial and spectral correlation
- CCSDS-123



- Applications
- Compression
- Unmixing
- Reducing prices



- Spectral unmixing is normally the first step in the analysis
- Pixels consist of a mixture of several materials
- Pure materials are named endmembers
- Abundances give the percentage of endmembers in a pixel

- Applications
- Compression
- Unmixing
- Reducing prices



- Multispectral cameras have lower prices
- DIY cameras





Hyperspectral technology: inspiring ideas, challenges and opportunities

Part II: HPC on-board Satellites

José López-Feliciano/Roberto Sarmiento Insitutte for Applied Microelectronics (IUMA)



Outline

- Satellites for Earth Observation and Spacecrafts
- Satellites on-board Hardware
 - System overview
 - Payload hardware
- Technology solutions for on-board HPSC
 - Radiation effects mitigation
 - FPGAs MPSoCs
- On-board Satellite payload data processing
 - New paradigm?
 - Data and Image Compression
 - Video Compression
 - Information Processing
- Conclusions

Satellites for Earth Observation and Space Crafts



Satellites by application	2013-2017	2018-2022
Earth Observation (EO)	58%	50%
Scientific	26%	16%
Technology	12%	10%
Communications	4%	22%
Novel applications	0%	3%

- Satellites
 - Low Earth Orbit(LEO)
 - Medium Earth Orbit (MEO)
 - Geosynchronous (GSO) & Geostationary (GEO)
 - Highly Elliptical Order (HE0)



Source: spaceaware.io

Iridium 119 (<u>October 9, 2017</u>) [783.2 / 786.3 km] Period: 100.4 minutes

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Satellites for Earth Observation and Space Crafts

- Satellites and debris
 - PL Payload
 - PF Payload Fragmentation Debris
 - PD Payload Debris
 - PM Payload Mission Related Object
 - RB Rocket Body
 - RF Rocket Fragmentation Debris
 - RD Rocket Debris
 - RM Rocket Mission Related Object
 - UI Unidentified

- Satellites
 - Commercial use satellites in low orbit has an exponential grow
 - Increase demand of *low-cost* systems for *high-performance space computing (HPSC)* and communications using commercial hardware
 - New era of remotely sensed big data!!



Source: ESA'S ANNUAL SPACE ENVIRONMENT REPORT, GEN-DB-LOG-00288-OPS-SD, 22 April 2022

Satellites for Earth Observation and Space Crafts

- Processing on-board is becoming mandatory
- From typical processing ...
 - Radiation correction
 - Geometric correction
 - Calibration
 - Compression
- ... to advanced processing:
 - Target detection
 - Classification
 - Cloud detection
 - Extract regions of interest (RoI) or crops of the scene
 - Artificial Intelligence
- "Satellite information services are moving from large-scale ground stations to on-vehicle, onboard, and hand-held terminals for receiving and transforming"



Bing Zhang, et al. **Progress and Challenges in Intelligent Remote Sensing Satellite Systems**, IEEE Journal Of Selected Topics In Applied Earth Observations And Remote Sensing, Vol. 15, 2022



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Satellite Hardware: system overview



- ESA SAVOIR (Space AVionics Open Interface aRchitecture)
- Complex but solved: modular solution

Satellite Hardware: system overview



• ESA SAVOIR (Space AVionics Open Interface aRchitecture)

Payload

Payload

commanding

Payload

Data Routing

Payload I/F Uni

Payload

Data Storage

Payload

Telemetry

Encryption

Security

Payload

synchronisation

TM CADUs • Complex but solved: modular solution



• High Performance Computing in Space??

Satellite Hardware: payload processing

- Acquisition system:
 - a) Fore-optics (telescope, slit assembly, and possibly depolarizer, etc.),
 - b) Optis for VNIR, SWIR spectrometers and possibly a panchromatic (PAN) channel,
 - c) Sensors (focal plane arrays, FPA) and their proximity electronics (PEs),
 - d) An onboard calibration unit,
 - e) A service module,

Discrete

signals

- f) Temperature sensors, heaters, etc.
- Processing system
 - a) PFCU: A processing formatting and control unit
 - b) MMU: A solid-state mass memory unit

Essential

ТΜ



Satellite Hardware: payload processing



Satellite Hardware: payload processing





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Radiation effects mitigation



Technology solutions for on-board HPSC

• The computing power of typical on-board computers is strongly limited by the volume, power and mass of nanosatellites.



ATF280F (Atmel,

180nm)





NGMP/GR740 Cobham Gaisler /ST/E2V/ESA





S-31 STOPTA

NGMP/GR740 (ST, 65nm)



VT65 (ST, 65nm)



CWICOM (Atmel, 180nm)

µProcessors/µControllers

It focus on computation, requires peripheral ICs, supports fastest generic computation, and has typical power consumption higher than 10 Watt.

FPGAs

It is a Re-programmable logic, has IPcores for specific and complete microcontrollers, provides fast and low power for specific functions, has higher power than micro-controllers.

OBDH

Hardware of the satellite on**board Data Handling** computing platforms

ASICs

It is a complete hardware solution for specific application, supports IP-cores for specific function, and has fast and power efficiency.

MP-SOCs

It provides a complete hardware and generic application. It has the smallest complete systems.



Kintex[™]UltraScale[™] XQRKU060



Technology solutions for on-board HPSC: FPGAs

- Programmable logic to provide configurability to the system:
 - SRAM technology:
 - The most used
 - Non-permanent
 - Reconfigurability
 - No radiation hardness
 - Antifuse technology
 - Permanent
 - Radiation hardness
 - One Time Programmable (OTP)
 - Best performance
 - FLASH memory
 - Permanent
 - Reprogrammable
 - Medium radiation hardness



FPGAs

Example FPGA: Rad Tolerant



	Virtex-4QV XQRV4QV	Virtex-5QV XQRV5QV	RT Kintex UltraScale XQRKU060
Radiation Hardness	Tolerant	Hard	Tolerant
Process (nm)	90	65	20
Memory (Mb)	4.1 to 9.9	12.3	38
System Logic Cells (K)	55 to 200	131	726
CLB Flip-Flops (K)	49.1 to 178.1	81.9	663
CLB LUTs (K)	49.1 to 178.1	81.9	331
Transceivers	None	18 at 3.125Gb/s	32 at 12.5Gb/s
User I/O	640 to 960	836	620
DSP Slices	32 to 192	320	2,760

Xilinx[®] Radiation Tolerant (RT) Kintex[®] UltraScale[™] XQRKU060 FPGA

- 20 nm technology
- Key advantages of RT Kintex UltraScale:
 - True Unlimited On-Orbit Reconfigurable Solution
 - >10X DSP Compute increase for Processing Intensive Algorithms & Analytics
 - Full Radiation Tolerance across All Orbits
 - 331K 6-inputs LUTs; 2760 DSPs.
- MicroBlaze[™] processor technology, fault tolerant, fail-safe, 32-bit RISC CPU, which can be instantiated within the FPGA.
 - This soft IP achieves a
 - performance above 300MHz
 - Requires approximately 7,400 LUTs and 6,400 flip-flops
 - Has been implemented using a TMR



FPGAs - MPSoCs

- 28 nm STMFDSOI process technology.
- On-chip thermal monitoring capability.
- Processors
 - A full System-On-Chip (SoC) based on a quad-core ARM Cortex R52
- FPGAs
 - 4-Input Look-up tables (536928 LUTs).
 - LUT expender to support up to 16 bits boolean functions.
 - Advanced interconnect network to support random logic and coarse grain block functions.
 - DSP Blocks for complex arithmetic operations (1344 DSPs).
 - User memories with variable width and depth.
 - Configuration modes: Master Serial SPI (Single, Sequential, TMR), SpaceWire.
 - Dedicated lowskew distribution network for clock, reset and load enable signals.

Interfaces

Integrated Space Wire interface available for user applications. Multiple I/O powering support from 1.2V to 3.3V Embedded logic to support DDR2, DDR3 and DDR4.

Radiation Tolerance

Radiation hardening by design in configuration memories and registers.

SEU immune up to LET > 60MeV.cm2/mg. Total ionizing dose > 50Krads (Si). Embedded EDAC for user memory mitigation. Embedded configuration memory scrubbing. Fast automatic memory configuration repair.

Embedded bitstream integrity check (CMIC).

Example MPSoC: Rad hard

NanoXplore NG-ULTRA: European FPGA



Radiation effects mitigation

Annual doses (Si) in circular equatorial orbits

computed with SHIELDOSE and AEBMAX, APBMAX models

4mm sphericol oluminium shielding.



Radiation annual dose

- Possibility to use COTS in many of LEO missions.
- But SEU errors are possible.
- Techniques to mitigate this errors:
 - Hardware Triple Module Redundancy (TMR) or Double Module Redundancy (DMR).
 - Software processing in two processors at the same time
 - Error Correction and Detection with Memories.
 - Memory scrubbing.
- Xilinx provides Soft Error Mitigation (SEM) IP:
 - Enhanced correction capabilities, essential bits monitoring and fault injection for validation.

Source: E.J. Daly, A. Hilgers, G. Drolshagen, and H.D.R. Evans, "<u>Space Environment Analysis: Experience</u> <u>and Trends</u>," ESA 1996 Symposium on Environment Modelling for Space-based Applications, Sept. 18-20, 1996, ESTEC, Noordwijk, The Netherlands

FPGAs – MPSoCs

Example MPSoC: : COTS HPSC

- Based on Zynq Ultrascale+
- XCZU4CG-2LE-I (low power, industrial temperature range).
 - 2 ARM Cortex-A53 up to 1.5 GHz for computing
 - 2 ARM Cortex-R5 up to 600 MHz for Real-Time.
 - NEON engine is a specialized vector processing engine.
 - 1 GB of DDR4-2400 with EDAC.
 - Programmable logic.
- External PS interfaces: I²C, SPI, CAN, RS-485, UART



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Digital processing on-board

- Calibration.
- Compression.
- Object detection.
- etc.

It is different in space? Yes!!!

- High processing power.
- Different missions: different objectives.
- Difficulties to adapt to different payloads, requiring custom solution.
 - i.e.: Earth observation vs. debris detection.

Space standards

• CCSDS standards.

Lack of testing data

HPSC: High Performance Space Computing

- It is hard to achieve onboard real-time processing without systematic optimization design for specific targets.
- "The key to a breakthrough is the development of new computing architectures, such as information extraction algorithms for non strict quantitative data processing".*
- Cross-level collaboration architectures of algorithm-software-hardware is required.
 - Heterogenous Computing.

Two examples:

- Adaptative compression based on cloud removal
- IA for object detection and tracking.

* Bing Zhang, et al. **Progress and Challenges in Intelligent Remote Sensing Satellite Systems**, IEEE Journal Of Selected Topics In Applied Earth Observations And Remote Sensing, Vol. 15, 2022

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Example 1 **Copernicus HPCM (High Priority Candidate Missions) CHIME (Copernicus Hyperspectral Imaging Mission For The Environment)**

Copernicus Hyperspectral Imaging Mission (CHIME)

The CHIME mission aims to augment the Copernicus space component with precise spectroscopic measurements to derive surface characteristics in support of the monitoring, implementation and improvement of policies in the domains of raw materials, agriculture, soils, food security, biodiversity, environmental degradation and hazards, inland and coastal waters, snow, forestry and the urban environment.

¥¥	
\$ \$	

Agriculture



Urban

Monitoring

€

Biodiversity

Monitoring

455 M EUR*



Volcanic Eruption at the Krýsuvík-Trölladyngja volcanic system, Iceland. This image, acquired by one of the Copernicus Sentinel-2 satellites on 23 March 2021, shows the volcanic eruption in Iceland's Reykjanes peninsula.



Volcanic Eruption in La Palma, Canary Islands, Spain. This Image acquired by one of the Copernicus Sentinel-2 satellites on 10 October 2021, shows the lava stream from the Cumbre Vieja volcano.

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Copernicus HPCM (High Priority Candidate Missions)Example 1CHIME (Copernicus Hyperspectral Imaging Mission For The Environment)

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Agriculture



Urban

Monitoring

Biodiversity

Monitoring



- System requirements:
 - Future space mission to complement COPERNICUS "Sentinels"
 - 2 Hyperspectral sensors (VNIR and SWIR) with 220 spectral bands each.
 - High volume of data => On-board Compression mandatory.
 - Clouds covers more than 50% of the Earth surface.
 - Significant presence of Clouds in CHIME continuous acquisitions.
 - Opaque Clouds are less useful to estimate Earth surface properties.
 - Possibilities to increase on-board data reduction with a selective compression applied on clouds.

COMP European Space Agency.

Thales Alenia Space in Spain. Thales Alenia Space in France.

- System requirements:
 - Performance requirements.
 - Real time: one sample per cycle.
 - 125 MHz of clock frequency.
 - Xilinx[®] Radiation Tolerant (RT) Kintex[®] UltraScale[™] QRKU060 FPGA

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Example 1



- Solution analysis
 - Solution 1: DSQ. Some bits of pixel-clouds are set to 0.
 - Solution 2: DAE. Different errors for pixel-clouds and pixelsno_clouds.
 - Solution 3: RtZ. Set the residuals of cloud-pixels to '0'.
- Best in performance RtZ (12% better than DSQ) but introduce outliers.
- Selected: **DAE** (Not the best but it doesn't create outliers).
- Tested with AVIRIS images.





Example 1
- Cloud detection and processing algorithms.
- Selected for implementation in the Demonstrator:
 - Cloud Detection: Support Vector Machine (SVM) approach
 - Cloud mask generation: indicates per each pixel if it is cloud (mask = '1') or not (='0')
 - Cloud Processing
 - Pre-quantization for the pixels detected as cloud to improve posterior compression in less useful areas



- Image reception up to 2Gbps (16 bit samples processed at 125 MHz clock cycle)
- Cloud detection over selected bands: Cloud mask
- Cloud processing
- CCSDS 123 Compression
- Data formatting: processed image + cloud mask
- Compressed image transmission
- TMTC (Telemetry and Telecommand) module for design configuration



• Demonstrator TEST Procedure



HW Description: KCU105 DUT board + UMFT601X-B Test Mezzanine

- UMFT601X-B Mezzanine
 - Manufacturer: FTDI
 - USB 3.0 to FIFO interface bridge
 - 2 parallel FIFOs with up to 32 bits at 66,67 MHz (Max 2,13344Gbps)
- KCU105 board
 - Manufacturer: Xilinx
 - FPGA: Xilinx Kintex Ultrascale, XCKU040-2FFVA1156E
 - External Memory: 16 Gb DDR4
 - Control interface: UART
 - Data Input and output interfaces: FMC connector
 - USB JTAG to program the FPGA



VIDEO



VIDEO IMAGING DEVICE FOR EARTH OBSERVATION

EXAMPLE 2





This project has received funding from the European Union's H2020 research and innovation programme under grant agreement No 870485.

igh Perfori



Video Imaging Device For Earth Observation

- The project aims to develop a highly-disruptive technology for a next-generation instrument offering Video Observation of Earth.
- A novel architecture will be demonstrated, based on state-of-the-art technologies for **mirrors** (freeform), **structures** (additive manufacturing) & **detection** (new generation detector & processing chain).
- It will allow to answer new types of problematics and missions, anticipating the emergence of on-board smart algorithms.
- Partners:
 - Thales Alenia in Space France SAS (coordinator)
 - Thales Alenia in Space Spain
 - University of Las Palmas de Gran Canaria
 - Poly-Shape (now AddUp)
 - Pyxalis
 - AMOS



Gigapyx RGB sensor from Pyxalis is expected to provide a large image in terms of spatial resolution (48Mpixels). 10 FPS for HD video sequences

• GOALS OF THE VIDEO CHAIN

- Capable of perform high-resolution RGB images and video monitoring on an extremely wide scene.
- Two modes of operation: detection (image mode) and compression plus tracking (video mode).
 - **Image mode:** detecting objects in the acquired scene.
 - Video mode: tracking of the object of interest and smart video compression of the ROI.
- Flying trajectory and speed known in advance \rightarrow Motion estimation seems not relevant.
- Adapt the video compression ratio depending on the satellite available resources and to the available downlink bitrates.
- Implemented on a Radiation Tolerant FPGA: Xilinx UltraScale XCKU060.



- Detection: Proposed detection solution
 - Based on convolutional neural networks (CNNs)
 - High detection capabilities
 - A single CNN architecture can be trained for different purposes.
 - The detection performance can be modified by replacing the pre-trained weights without modifying the network architecture.

High Level tools: Python - Keras, Tensorflow

Training of the CNN:

- Different weights depending on use case.
- NN can be re-trained and weights uploaded via the uplink.



R. Neris, A. Rodríguez, R. Guerra, S. López and R. Sarmiento, "**FPGA-Based Implementation of a CNN Architecture for the On-Board Processing of Very High-Resolution Remote Sensing Images**," in IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing, vol. 15, pp. 3740-3750, 2022, doi: 10.1109/JSTARS.2022.3169330.

Y. Barrios, R. Neris, R. Guerra, S. López and R. Sarmiento, "Speeding up FPGA Prototyping on Space Programs with HLS Workflow. Use Case: Video Compression On-board Satellites," 2022 37th Conference on Design of Circuits and Integrated Circuits (DCIS), Pamplona, Spain, 2022, pp. 01-06, doi: 10.1109/DCIS55711.2022.9970056.

- Detection: architecture overview
 - 10 different architectures analyzed at Keras.
 - MobileNet-Reduced:
 - Good compromise between accuracy and complexity.
 - Number of filters divided by 4 compared to standard MobileNet.
 - Detection strategy:
 - Each video frame will be independently processed as an RGB image by the CNN.
 - Processing the received lines without waiting for the full image.
 - Each image will be processed applying a sliding window with a certain stride and overlap.
 - A window size of 256x256 pixels should give enough margin for target detection.

The window moves from left to right and from top to bottom.



Ship detected.







- reduction in the number of filters by a factor of 4
- activation of the *shallow* option which removes five stages of the network.
- This modified architecture, named MobileNetv1Lite, gives a reduction of 96.15% in the number of trainable parameters.

Example 2

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• System: Test Set-up

- The whole video processing have been validated.
 - A test set-up has been developed on a Xilinx Kintex UltraScale XCKU040 FPGA.
 - The whole validation set-up also runs at a clock frequency of **200 MHz**, except the DDR4 controller (300 MHz).
- A test dataset comprised by short video sequences where boats are captured at different locations was created.
- Three outputs are generated (one per compression instance) and sent back to the control PC, independently decompressing them with an in-house software compliant with the CCSDS 123.0-B-2 standard.
 - The three decompressed files are merged into a single YCbCr video sequence for visualization purposes.

Module	BRAMs	DSPs	Registers	LUTs
Detection Network	229.5 (38.3%)	1405 (73.1%)	134284 (27.6%)	136960 (56.5%)
Video compressor	322 (53.6%)	176 (9.3%)	37557 (7.9%)	44660 (18.4%)
TOTAL	551.5 (91.9%)	1581 (82.3%)	171841 (35.5%)	181620 (74.9%)







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Conclusions High Performance Space Computer

- New Space (NS) is a completely new approach.
 - Smaller satellites.
 - More computation on-board.
 - Shorter earth-to-Space time.
 - Constellations (mainly in Low Earth Orbit).
 - Private funding.
 - One satellite many solutions.
- HPSC: High Performance Space Computing is a hot topic today.
 - Modular systems.
 - Demand computing on-board.
 - Standardization is required.
 - Needs to use the last technological advances (FPGAs, etc).
 - Using COTS for LEO orbits.
- Example 1: CHIME mission.
 - New mission in the Copernicus program.
 - Long life with public information.
 - Reduce information on cloudy scenes.
- Example 2: European VIDEO project.
 - Use a complex approach for Space.
 - Image mode and video mode.
 - CNN for ship detection with possibility to adapt.







Conclusions Future of HPSC

- AMD-Versal MPSoC
 - Full system on a chip
 - 2xARM Cortex-A72; 2X ARM Cortex-R5F; AI Engine; DSP-Engine; Programmable Logic; NoC; etc. etc.
- RISC-V
 - New standard on Space?
 - Link between HPSC and HPC on ground?
 - Solutions: NOEL-V, Microchip Polarfire, De-RISC, Occamy, etc.
 - ESA: The RISC-V in Space Workshop, 12/2022 <u>http://microelectronics.esa.int/riscv/rvws2022/index.</u> <u>php</u>
- GPUs
 - Nvidia Jetson Nano, TX1, etc.
 - W. S. Slater, N. P. Tiwari, T. M. Lovelly and J. K. Mee, "*Total Ionizing Dose Radiation Testing of NVIDIA Jetson Nano GPUs*," 2020 IEEE High Performance Extreme Computing Conference (HPEC), Waltham, MA, USA, 2020, pp. 1-3, doi: 10.1109/HPEC43674.2020.9286222.
 - C. Adams, A. Spain, J. Parker, M. Hevert, J. Roach and D. Cotten, "Towards an Integrated GPU Accelerated SoC as a Flight Computer for Small Satellites," 2019 IEEE Aerospace Conference, Big Sky, MT, USA, 2019, pp. 1-7, doi: 10.1109/AERO.2019.8741765.
- Quantum computing
 - Disruptive computing in this workshop!





Hyperspectral technology: inspiring ideas, challenges and opportunities

Part III: Additional projects

José López-Feliciano/Roberto Sarmiento Institute for Applied Microelectronics (IUMA)



Outline

- The institute for Applied Microelectronics at ULPGC
- Why hyperspectral technology?
 - Some numbers
 - Applications
- Introduction to hyperspectral technology
 - The human eye
 - Multi- vs hyperspectral sensors
 - Types of hyperspectral sensors
- Ongoing projects
 - Space
 - Precision agriculture
 - Environment
 - Health













SPACE

SPACE



- Cosmódromo de Plesetsk
 1966
 1957-2021: 1589 lanzamientos
- Cosmódromo de Baikonur 1957

1957-2021: 1431 lanzamientos

- Cabo Cañaveral
 1958
 1957-2021: 935 lanzamientos
- 4. Base Aérea Vandenberg 1959 1957-2021: 625 lanzamientos
- 5. Puerto Espacial Kourou 1970 1957-2021: 296 lanzamientos

SPACE

Velocity at Earth's Surface by Latitude



SPACE





San Marco Platform (Kenya) 1964-1988

SPACE





29/06/2023





















PRECISION AGRICULTURE



NDVI false color image of a vineyard (taken from a UAV in Gran Canaria)

PRECISION AGRICULTURE



29/06/2023



ENVIRONMENT



Plataforma Oceánica de Canarias
ENVIRONMENT



ENVIRONMENT

CURRENT LINES OF STUDY

- Spectral analysis of oil spills
- Unsupervised semantic segmentation NN
- Detection of floating debris at sea







ENVIRONMENT

• DEEP WATER HORIZON

Location: Gulf of Mexico in 2010 Duration of discharge: 3 months

NORMALIZED DIFFERENCE OIL INDEX

$$NDOI = \frac{\lambda_{599} - \lambda_{870}}{\lambda_{599} + \lambda_{870}}$$

AVIRIS SENSOR

224 bands in VNIR-SWIR



ENVIRONMENT

MOST CITED INDICES FOR IDENTIFYING SPILLS.

Index	Equation	Measured property
RAI	(Blue - IR) / (Blue + IR) $\sqrt{\sum_{i=1}^{N} b_i^2}$	Oil fluorescent characteristics
FI	(Blue - Red) / (Blue + Red)	Oil fluorescent characteristics
OSI	$(DN_{\lambda_{Red}} - DN_{\lambda_{Yellow}})/(\lambda_{Red} - \lambda_{Yellow})$	Existence of crude oil
CDOM	R_{565}/R_{660}	Seawater characteristics
CHL	$log(max(R_{433,490,510})/R_{555})$	Surface chlorophyll a
NDVI	(NIR - Red) / (NIR + Red)	Live green vegetation



ENVIRONMENT





ELECTRICAL VTOL

ENDURANCE Aprox. 6 hors

ECONOMICAL SOLUTION

29/06/2023

High Performance and Disruptive Computing in Remote Sensing

ENVIRONMENT





MTOW	4000 kg		
PAYLOAD	1850 kg		
ENDURANCE	25 hours		
AUTONOMOUS			
AMPHIBIOUS			
REMOTELY PILOTED			

HEALTH

NEW BRAIN CANCER DECISION SYSTEM

The main goal of the HELICoiD project is to apply hyperspectral imaging techniques to the precise localization of malignant tumours during surgical procedures. The HELICoiD project will develop an experimental intraoperative setup based on non-invasive hyperspectral cameras. This will be connected to a platform running a set of algorithms which are capable of discriminating between healthy and pathological lissues. The prototype will be developed with the aim of recognising cancer tissues during the surgical procedure in real time. This information will be provided to the surgeon via different display devices, and in particular by overlaying the conventional images with a simulated colour map to indicate the probability of any currently exposed tissue being cancerous. To meet these real time and in vivo cancer detection requirements, a hardware/software partitional loaf requirements of the algorithms which are developed.

The integration of hyperspectral imaging and intraoperative imagedguided surgery systems should have a direct impact on patient outcomes. Potential benefits include: allowing confirmation of complete resection during the surgical procedure, avoiding complications due to "body mass shift", and providing confidence that the goals of the surgery have been achieved.

A multidisciplinary consortium composed of surgeons, pathologists, ICT engineers, mathematicians and physicists has been created. Two European hospitals will be involved, as end-users, in setting the requirements for, and conducting validation of, the tools and systems developed within this project. If hyperspectral imaging techniques are demonstrated to be practical for surgical applications then it is expected that European industry related to hyperspectral imaging will be well placed to exploit this opportunity for growth.

ons, and tals liceal urobe

To offer the best prospects for success, this project will adopt the algorithms-architecturesimplementations co-exploration paradigm. It is our belief that translation of hyperspectral image technology to real-time medical applications cannot be achieved by developing algorithms, architectures and implementations separately. Rather, this goal is better served by adopting a fully integrated approach from the outset.



Project co-ordinator:

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Pictures:

1: Brain cancer operation at University Hospital Dr. Negrin.

 HELICoID hyperspectral cameras.
Surgeons and operation theatre at University Hospital Dr. Negrin.

 Simulation of the surgeons display with the results of the algorithm. Real image and tumour map.



* Disclaime

Co-funded by the European Union which might be made of this information.

Published by the HELICoiD project consortium.

HELICoiD

HypErspectral Imaging Cancer Detection

FP7-618080 (FP7-ICT-2013-C)

A Collaborative Project supported by the Seventh Framework Programme of the European Comission

CHALLENGES OF BRAIN CANCER DETECTION

Brain cancer is one of the most important forms of the disease, and is a significant economic and social burden across Europe. The most common form is high-grade malignant glioma, which accounts for approximately 30-50% of primary brain cancers, with multiform glioblastoma making up 85% of these cases. These types of gliomas are characterized by fastgrowing invasiveness, which is locally very aggressive, are in most cases unicentric and are rarely metastasizing.

Despite the introduction of new aggressive treatments combining surgery, radiotherapy and chemotherapy, there continues to be treatment failure in the form of persistent or locally recurrent tumours (i.e. recurrence at the primary tumour location or within 2-3 cm of adjacent tissue). Median survival periods and 5-year survival rates for anaplastic astrocytomas are only 36 months and 18% respectively, whereas for glioblastoma multiforme these are 10 months and less than 5%, respectively.

The relevance and importance of complete resection for low grade turnours is well known, especially in paediatric cases. However, traditional diagnoses of internal turnours are based on excisional biopsy followed by histology or cytology. The main weakness of this standard methodology is twofold: firstly, it is an aggressive and invasive diagnosis with potential side effects and complications due to the surgical resection of both malign and healthy tissues; and secondly, diagnostic information is not available in real time and requires that the tissues are processed in a laboratory.

There are several alternatives to conventional optical

visualisation through a surgical microscope, including

magnetic resonance imaging (MRI), computed tomo-

graphy (CT), ultrasonography, Doppler scanning and

nuclear medicine. Unlike these approaches, hypers-

pectral imaging offers the prospect of precise detec-

tion of the edges of the malignant tissues in real time

during the surgical procedure.



HEALTH

Verification Using In-Vivo Surgical Data



29/06/2023





(a)



High Performance and Disruptive Computing in Remote Sensing

